

NCHRP 3-65: Applying Roundabouts in the United States

Operations



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Presentation Outline

- **Analytical Computation**
- **Driver Behavior and Geometry**
- **Model Comparison/Calibration**
- **Model Selection**

Capacity Models Tested

Empirical Models

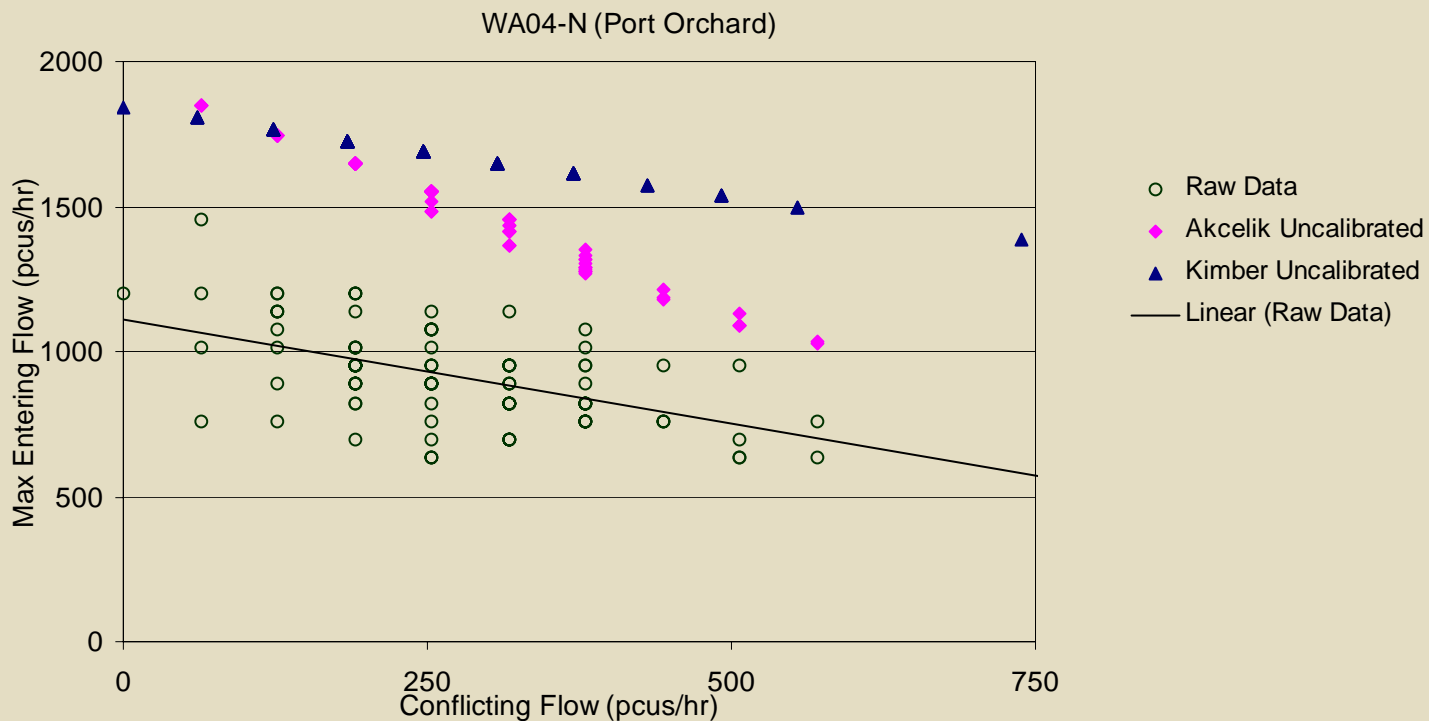
<i>COUNTRY</i>	<i>NAME</i>	<i>TYPE</i>	<i>VARIABLES</i>
➤ <i>British</i>	<i>RODEL/Kimber</i>	<i>Linear</i>	<i>geometry</i>
➤ <i>French</i>	<i>GIRABASE/Louah</i>	<i>Exponential</i>	<i>geometry + tf/tc</i>
➤ <i>Swiss</i>	<i>Lausanne</i>	<i>Linear</i>	<i>geometry</i>
➤ <i>Israel</i>	<i>Polus</i>	<i>Exponential</i>	<i>speed</i>
➤ <i>FHWA</i>	<i>Simplified British</i>	<i>Linear</i>	<i>NA</i>

Analytical Models

➤ <i>German Wu</i>	<i>tf/tc</i>	
➤ <i>Australian SIRDA/Troutbeck</i>	<i>tf/tc</i>	<i>limited geometry</i>
➤ <i>HCM</i>	<i>tf/tc</i>	

Analysis of Exiting Models

- **All international models (including SIDRA and RODEL) predict capacities higher than observed**



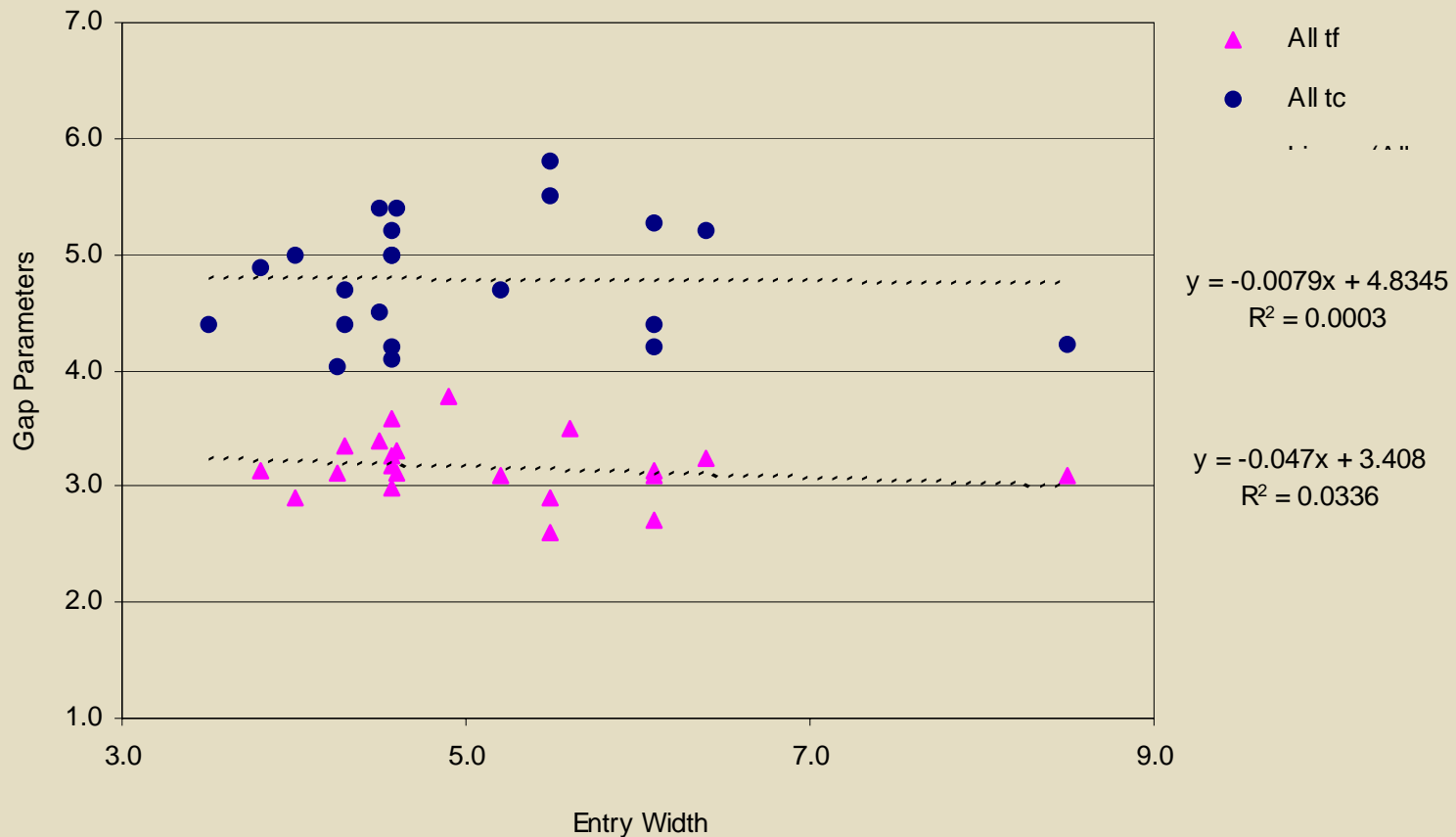
Field Measured Gap Acceptance Parameters

'Average' approach critical gap and follow-up times

Model		1 Lane		2 Lane	
		tf	tc	tf	tc
Field	Right lane	2.6-4.3	4.2-5.9	2.7-4.7	3.5-4.9
	Left lane			2.8-4.4	4.2-5.5
HCM		3.1	4.6	NA	NA
German		3.2	4.4	3.2	4.4
French		2.1	NA	2.1	NA
Akçelik Dominant SubDom		1.8-2.7	1.4-4.9	1.8-2.8 2.2-4.0	1.6-4.1

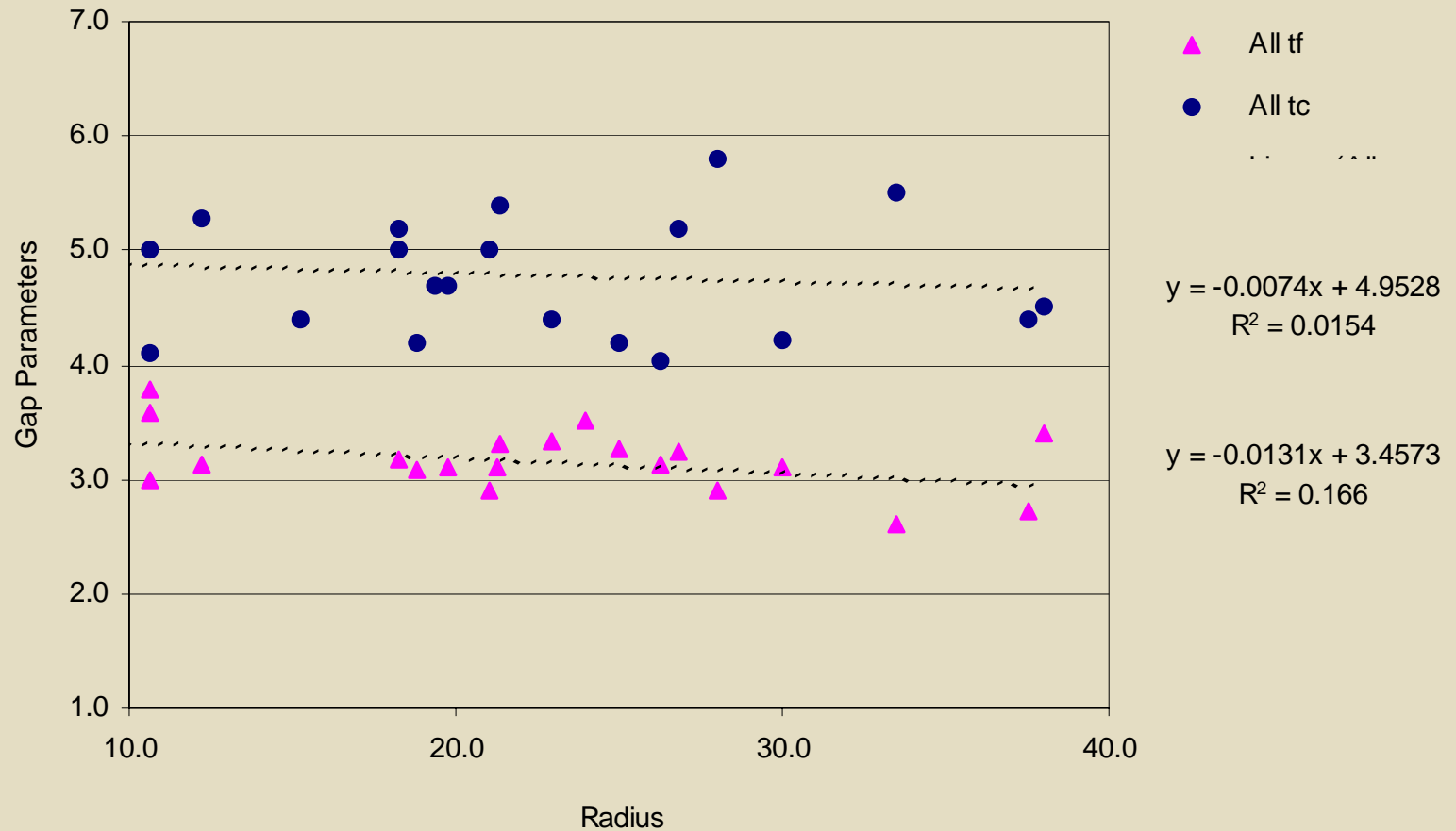
Influence of Flow & Geometry on Driver Behavior

- **Entry lane width = entry width / #lanes**



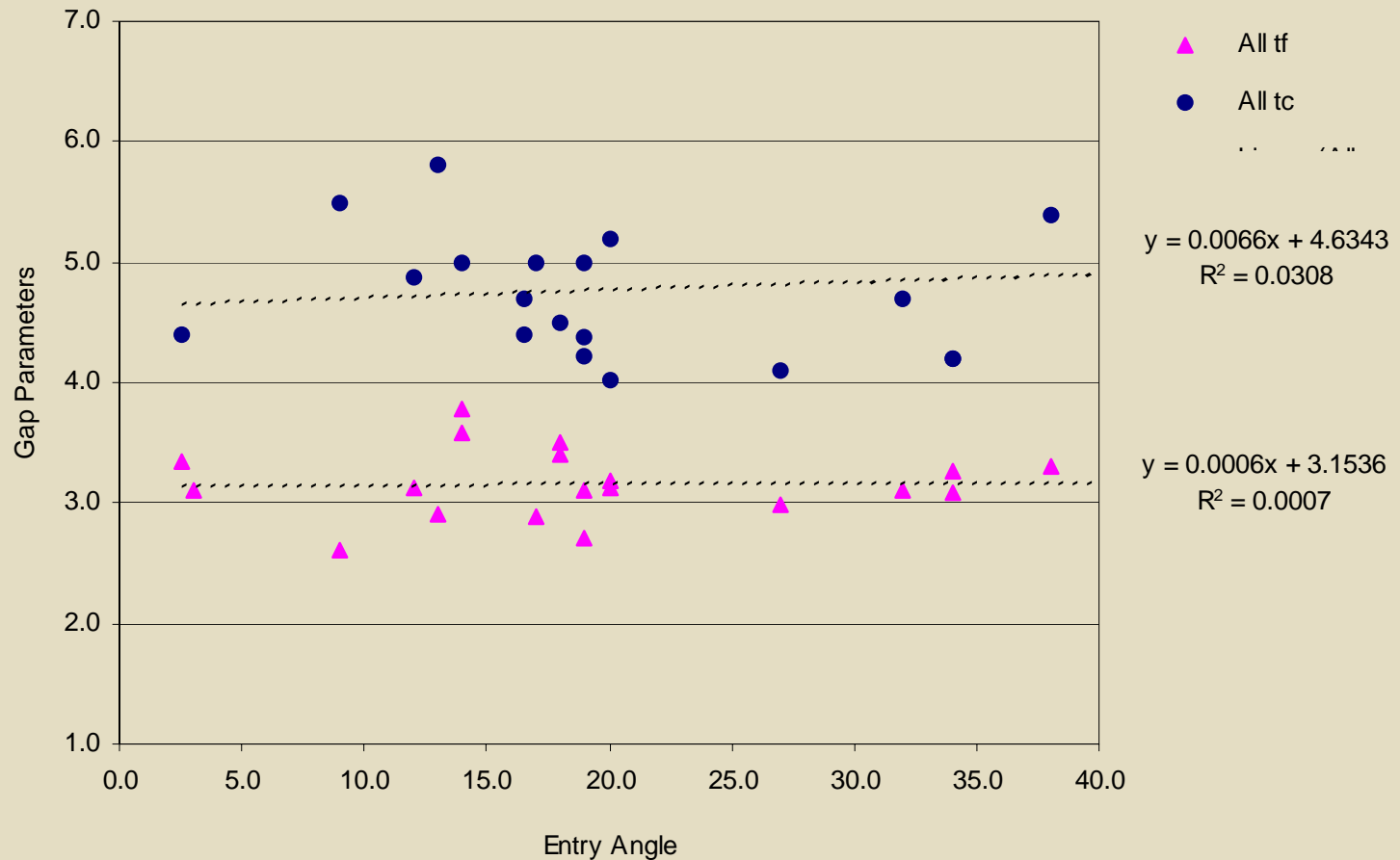
Influence of Flow & Geometry on Driver Behavior

■ Radius



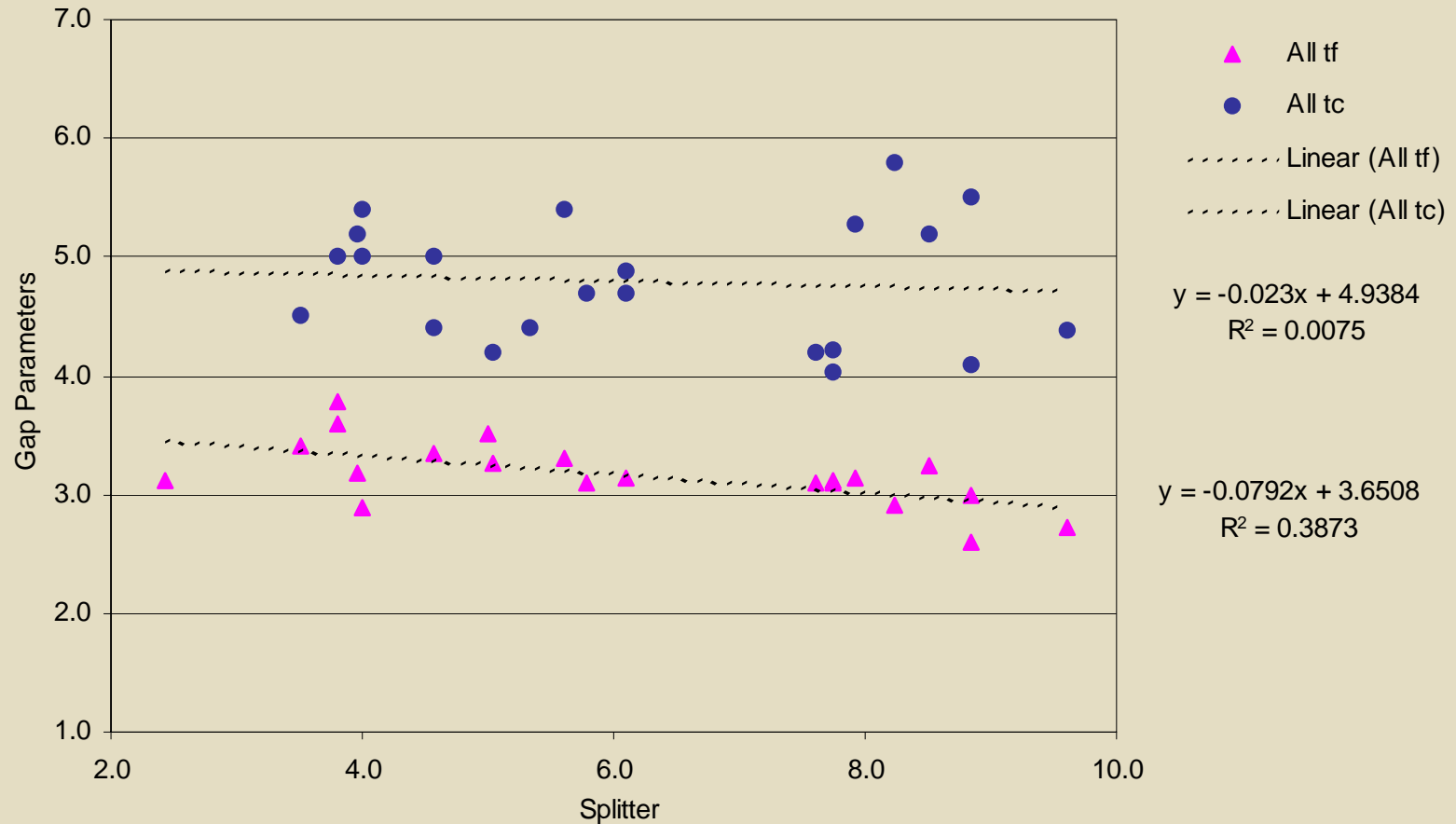
Influence of Flow & Geometry on Driver Behavior

■ Entry Angle



Influence of Flow & Geometry on Driver Behavior

■ Splitter Width

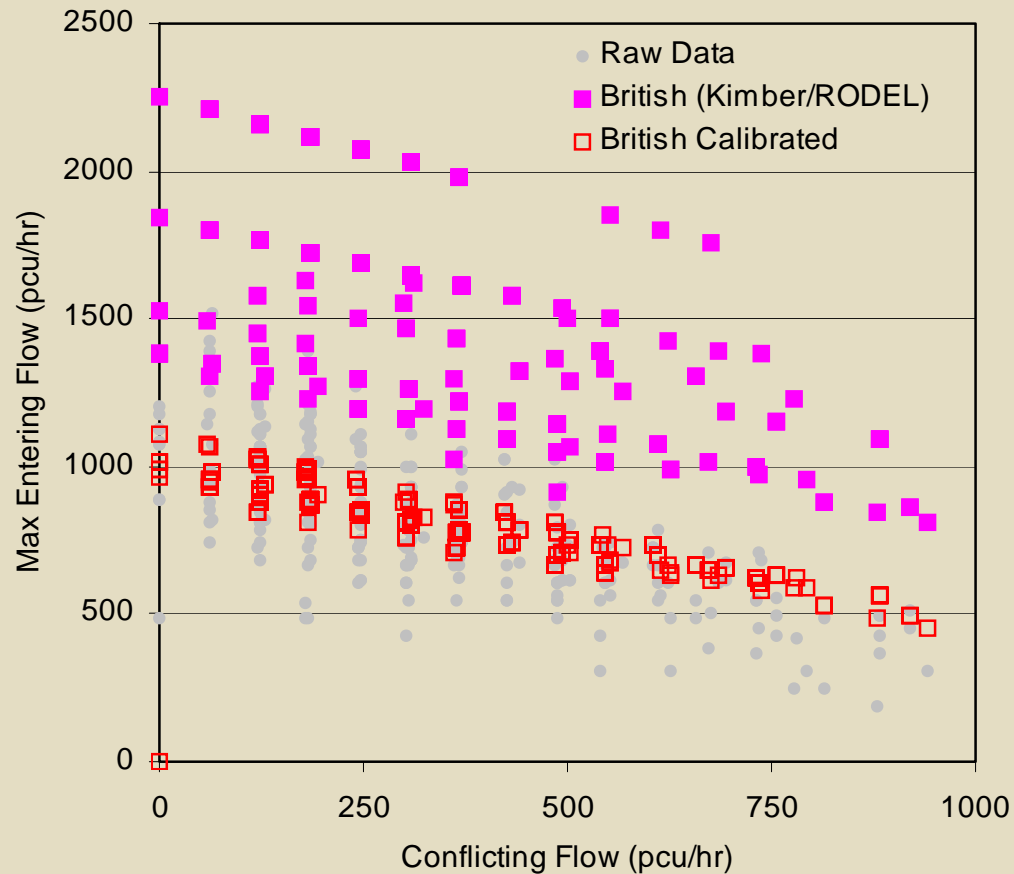


One Lane Calibration

MODEL	None (All veh/hr)	<i>pcus</i>	<i>geometry</i>	<i>geometry & F</i> (1L sites only)	<i>geometry & F</i> (All sites)	<i>geometry tf; tc</i>	<i>Include exit + 100% conflicting</i>
						<i>mup<6</i>	<i>mup<6</i>
<i>Kimber</i>	795	773	421	167	169	-	228
Akcelik	593	545	-	-	-	160	440
Kreisel	294	215	-	-	-	143	396
French	1191	1234	-	-	-	258	-
Swiss	376	343	-	-	-	323	-
HCM Upper	326	322	-	-	-	145	342
HCM Lower	180	176	-	-	-	-	-
FHWA	240	224	-	-	-	-	270

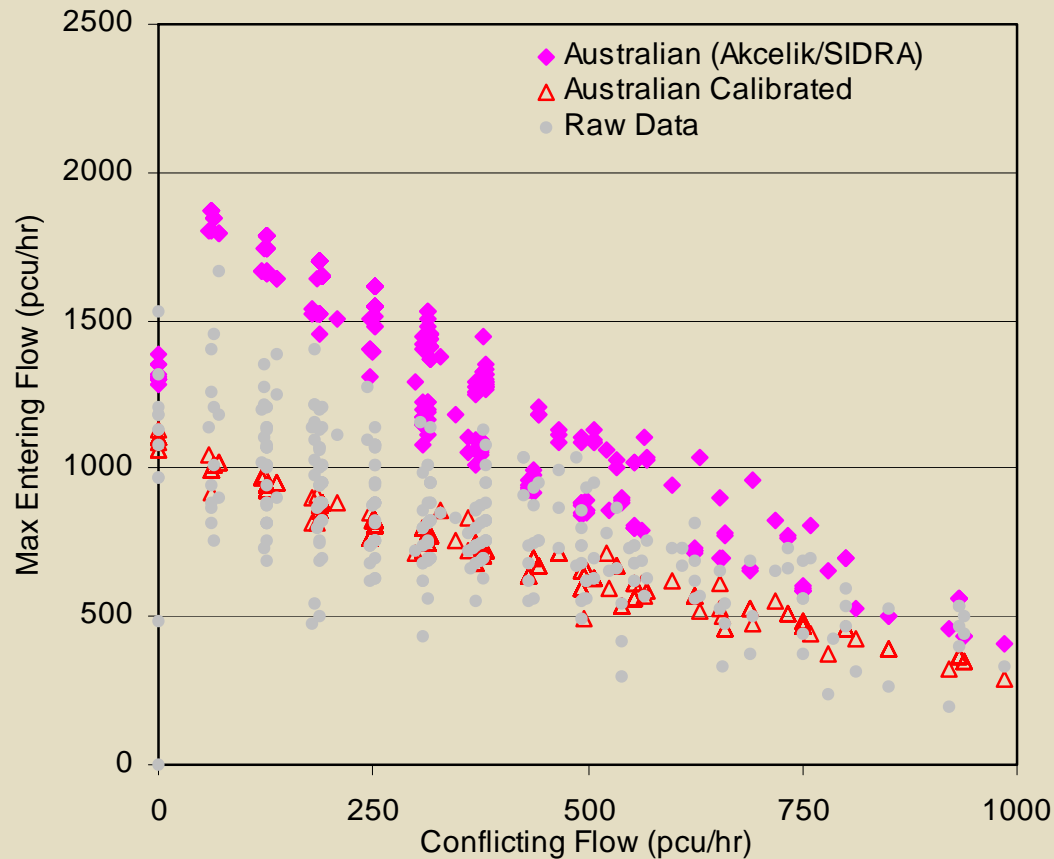
One Lane Calibration

- **British – All single lane approaches**



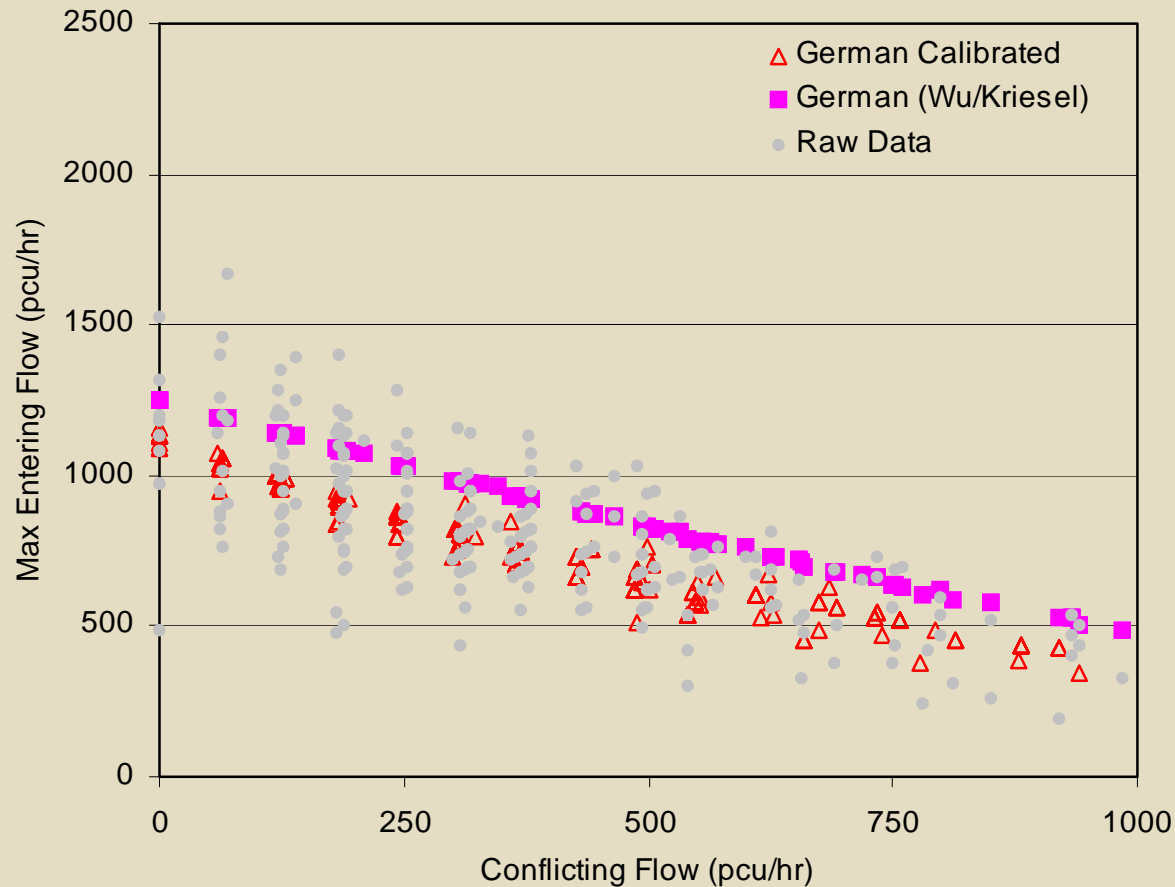
One Lane Calibration

- **Australian – All single lane approaches**



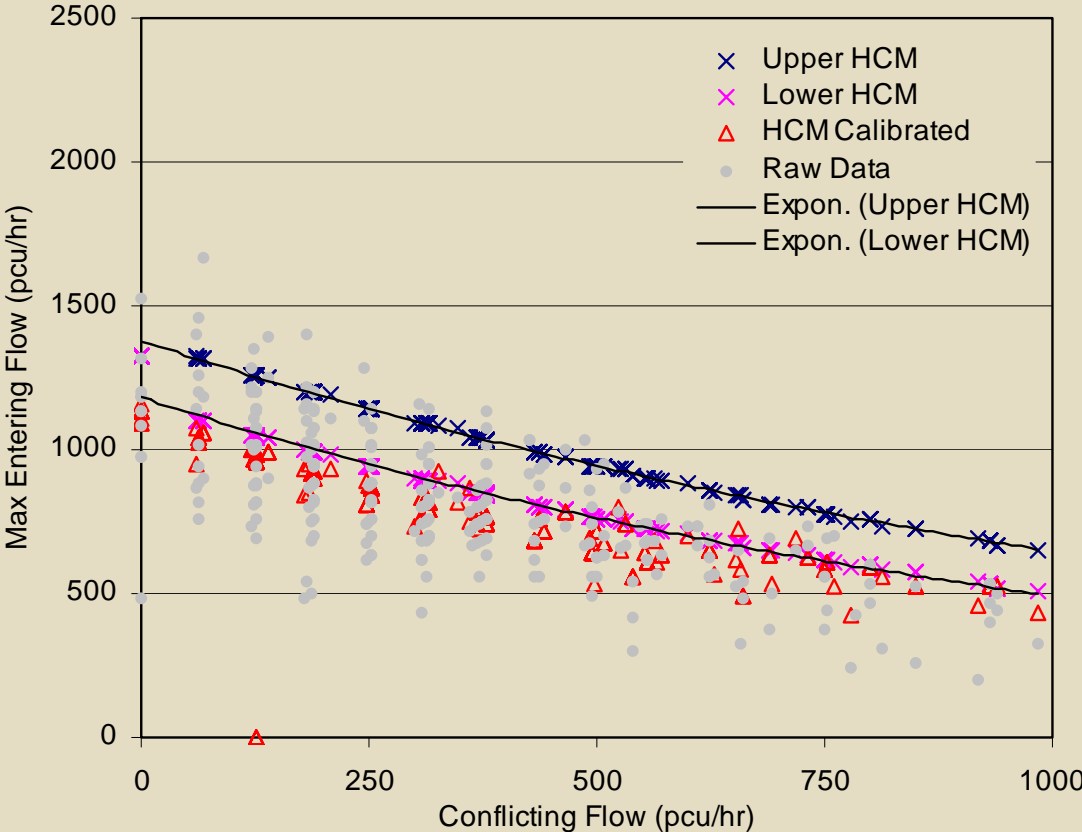
One Lane Calibration

- **German – All single lane approaches**



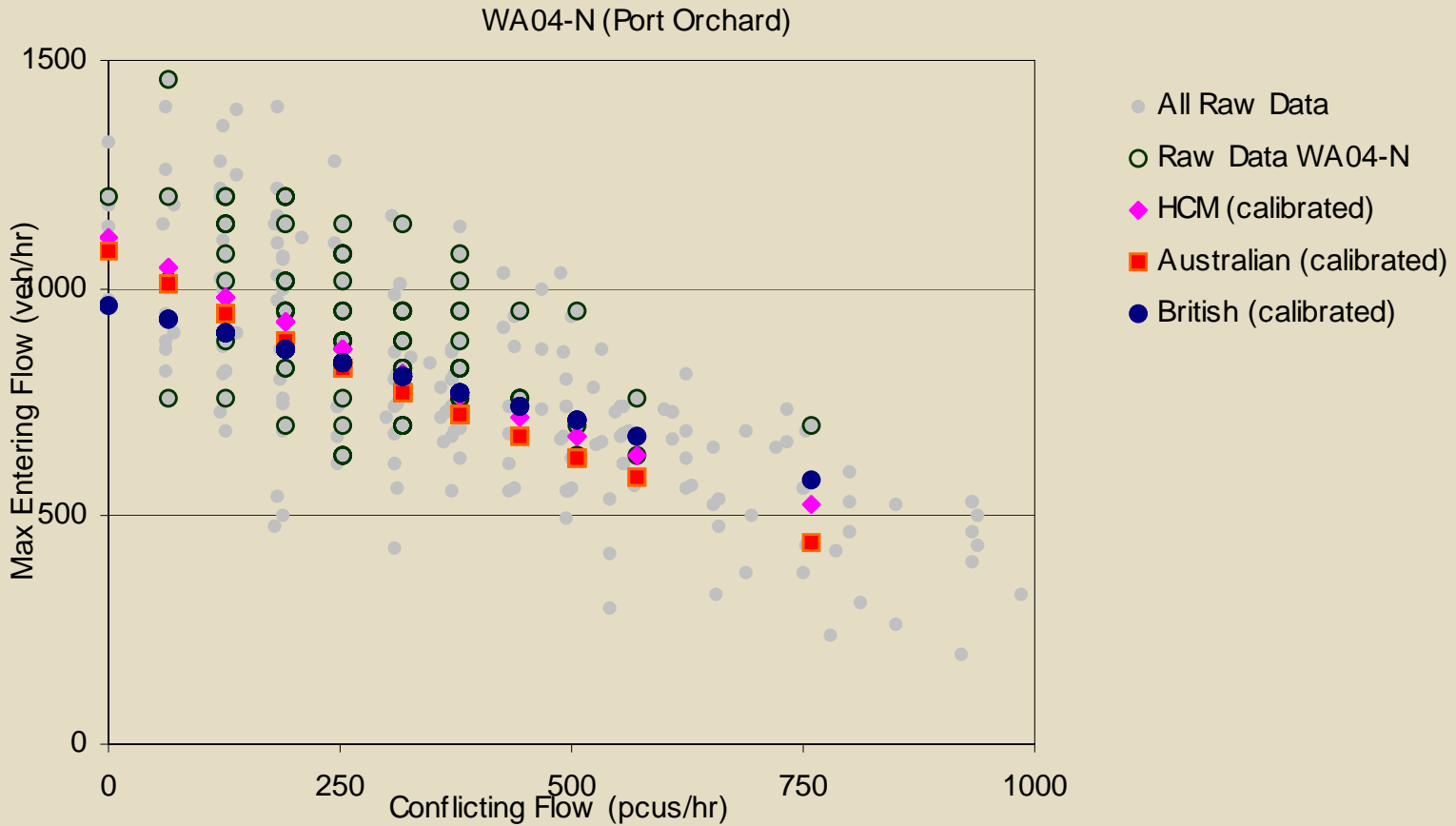
One lane Calibration

- HCM – All single lane approaches**



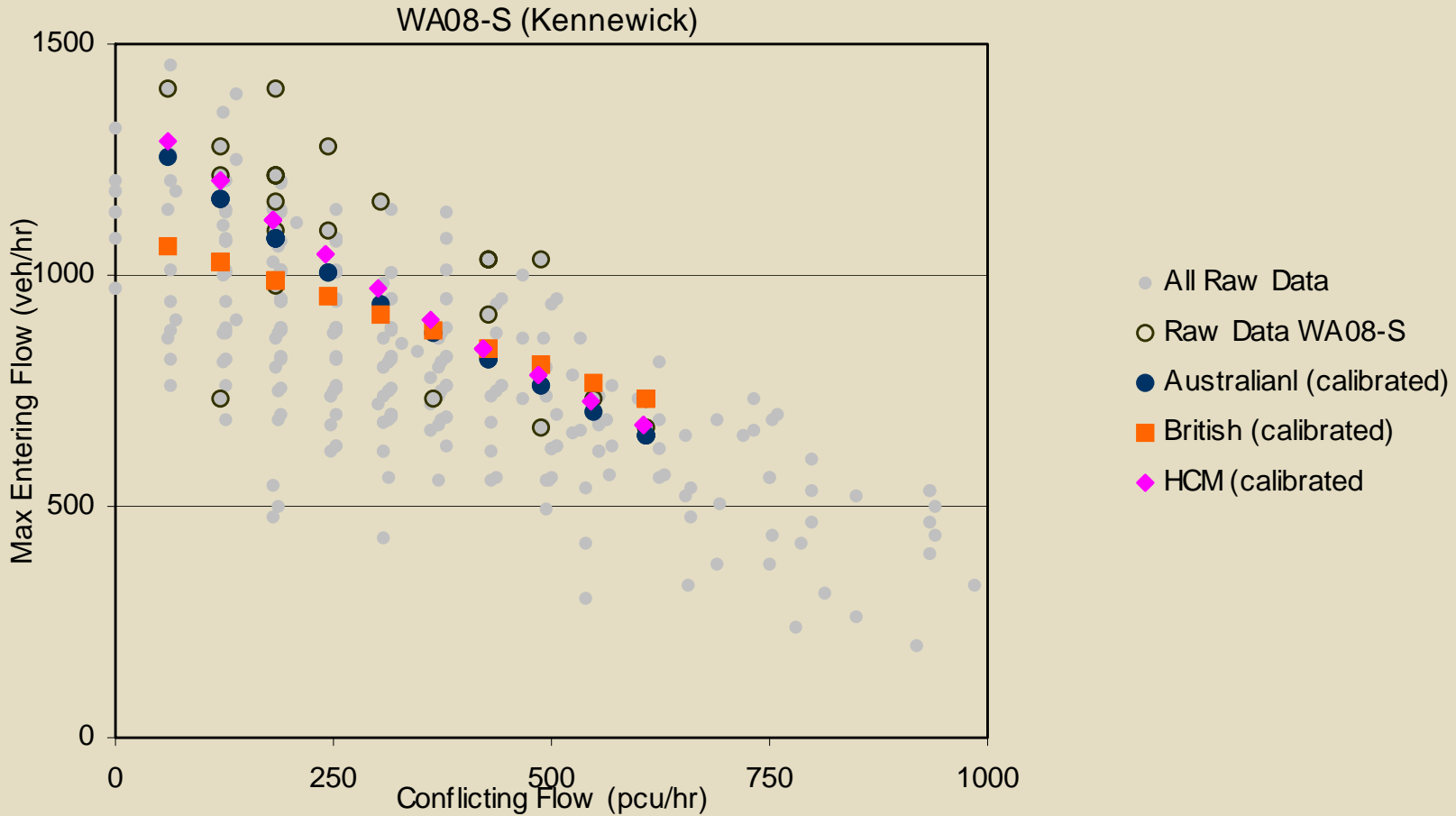
One Lane Calibration

■ Port Orchard north (average entry flow)



One Lane Calibration

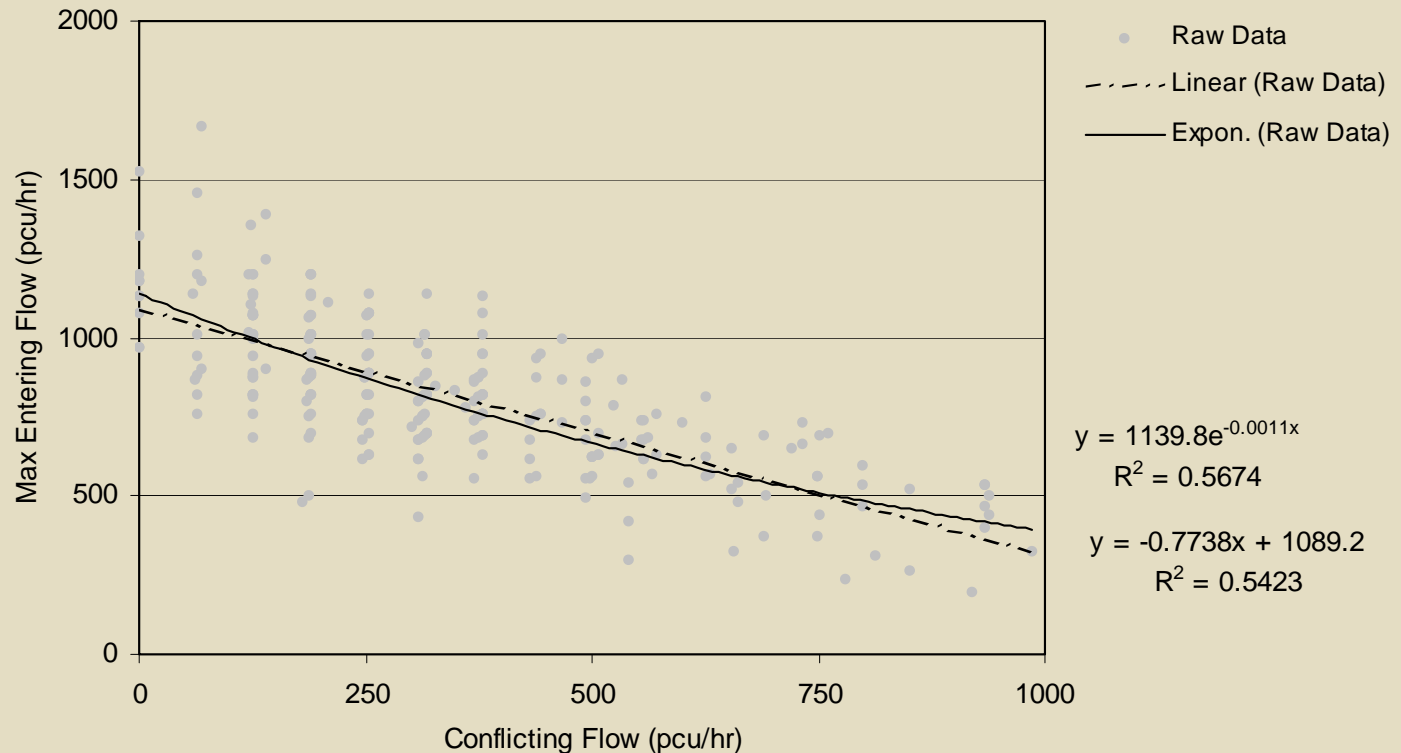
■ Kennewick south (high entry flow)



One lane Calibration

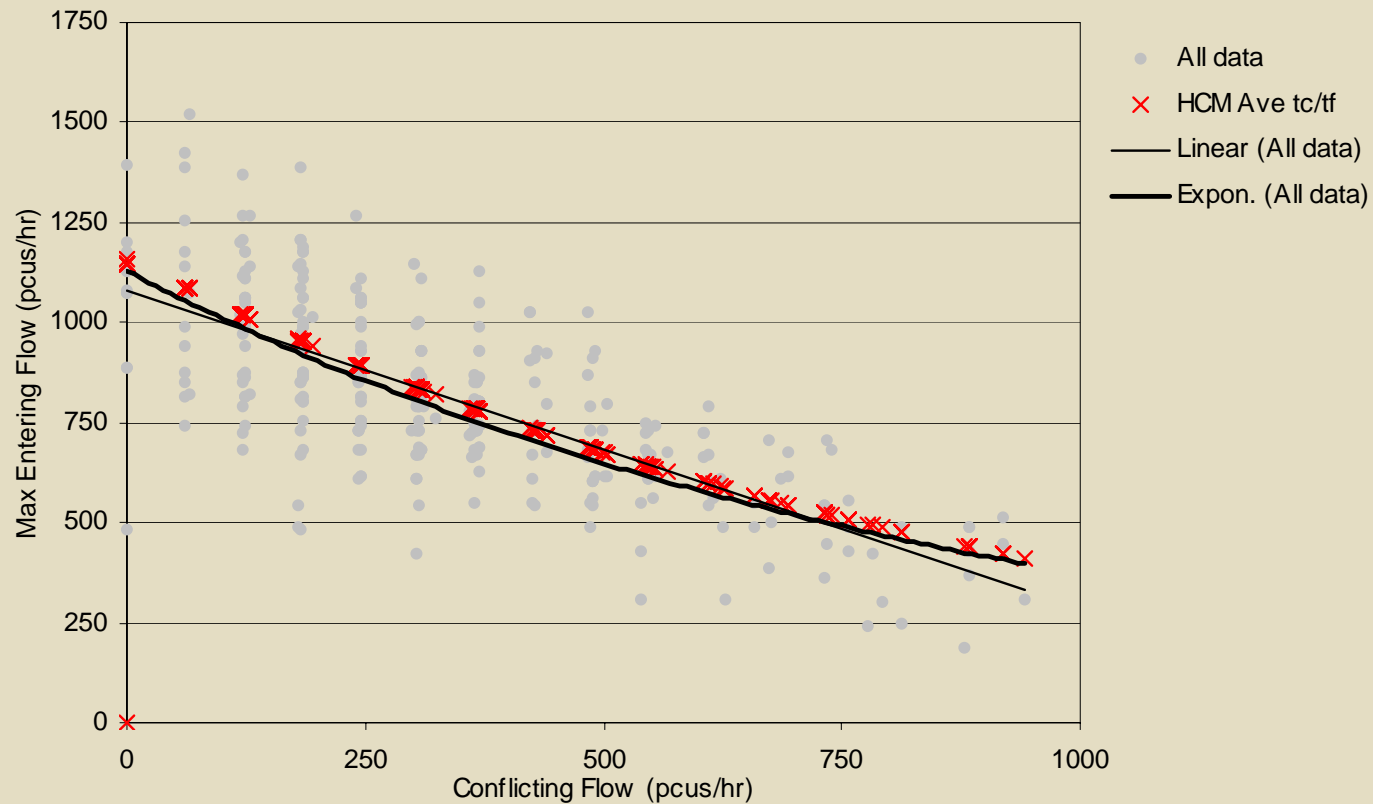
■ Linear or exponential regression

➤ $RMSE = 160$



Critical Gap and Follow-up time estimates

- **Average critical gap and follow-up time similar to using regression**



Multi-Lane Calibration

- **Several sites exhibit strong queuing in only one lane**
 - Turning movement effects
 - Other possible constraints (path overlap, etc.)

	LEFT LANE	RIGHT LANE	L	T	R	U	Comment
WA09-e	18%	82%	9%	86%	5%	1%	10% of Throughs in LL
MD04-E	55%	45%	72%	28%	1%	0%	20% of Lefts in RL
MD05-SW-NW	0%	100%					
MD05-SW-W	0%	100%					
VT03-E	45%	55%	30%	49%	21%	0%	50% of Lefts in RL; 15% of Throughs in LL
VT03-S	33%	67%	28%	39%	31%	3%	
VT03-W	35%	65%	19%	32%	46%	4%	

Multi-Lane Calibration

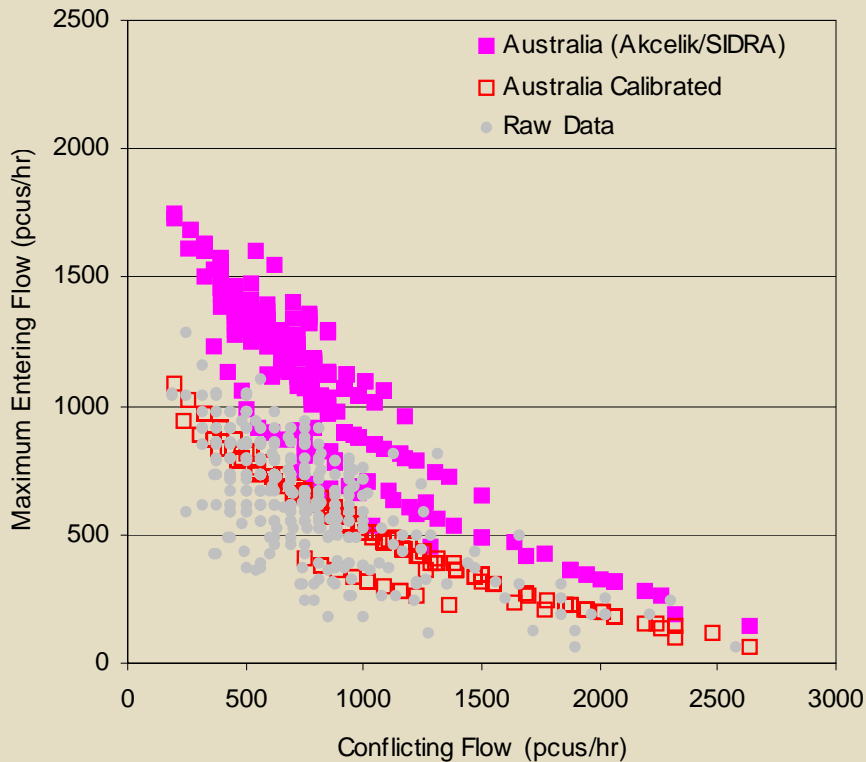
■ Multi-Lane Summary

MODEL	LANE	# Obs	None (All veh/hr)	<i>pcus</i>	<i>geometry &F</i>	<i>geometry &F</i> (All Sites)	<i>geometry tf;</i> <i>tc</i>
							<i>mup<6</i>
<i>British</i>		143	1057	982	270	324	-
Austalian	Right	385	478	480	-	-	163
	Left	120	480	488	-	-	189
German		143	385	323	-	-	257
French		128	821	692	-	-	230
Swiss		143	528	444	-	-	-
HCM Lower		143	272	320	-	-	372
HCM Upper		143	368	426	-	-	
FHWA		71	953	857	-	-	-

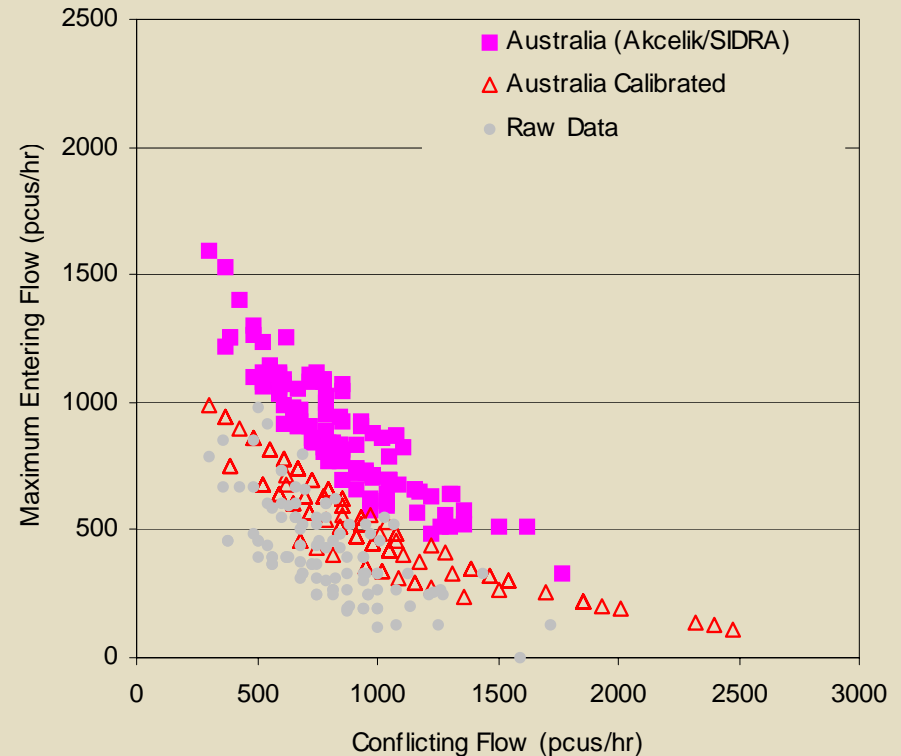
Multi Lane Calibration

- Australian - All multilane approaches
- Lane based model

All - Right

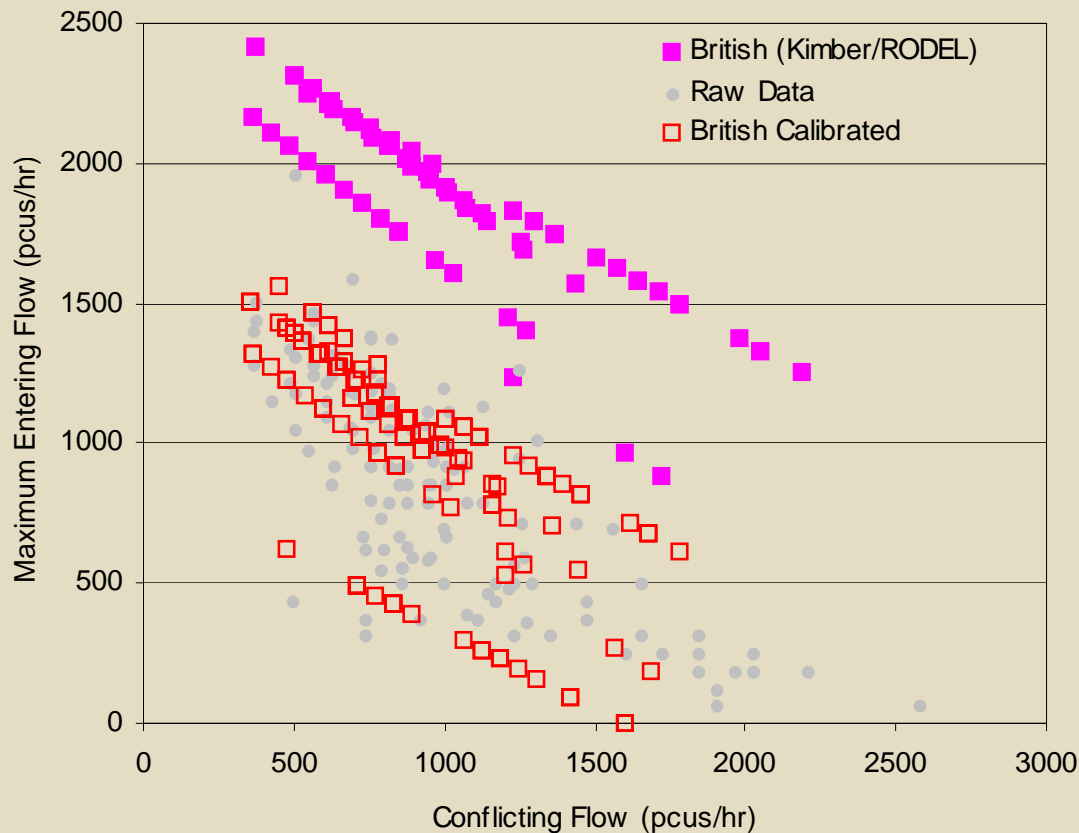


All - Left



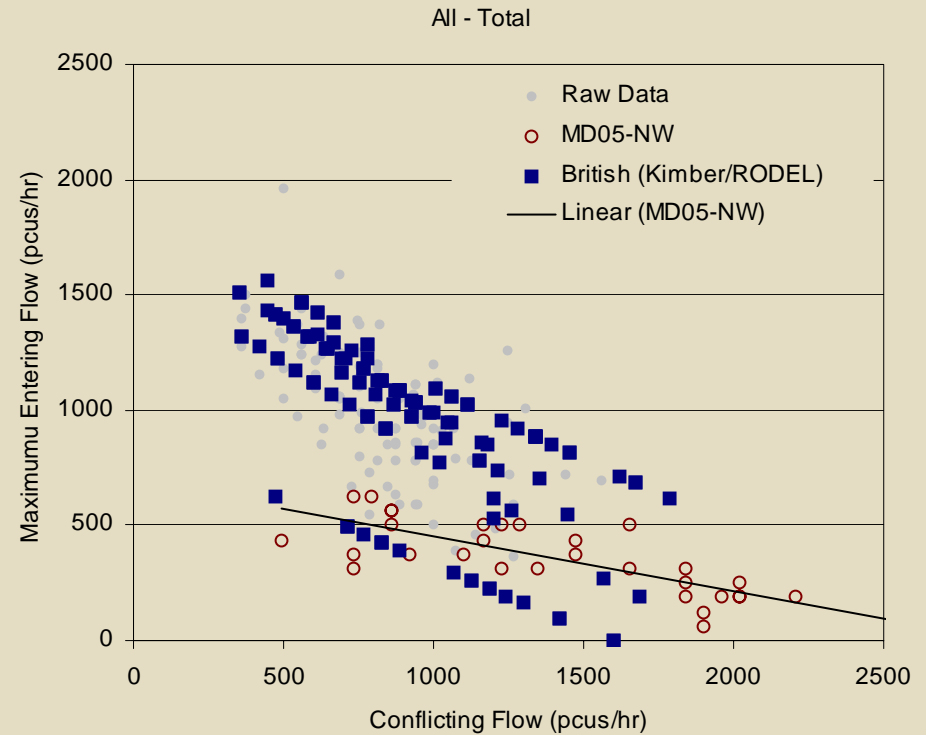
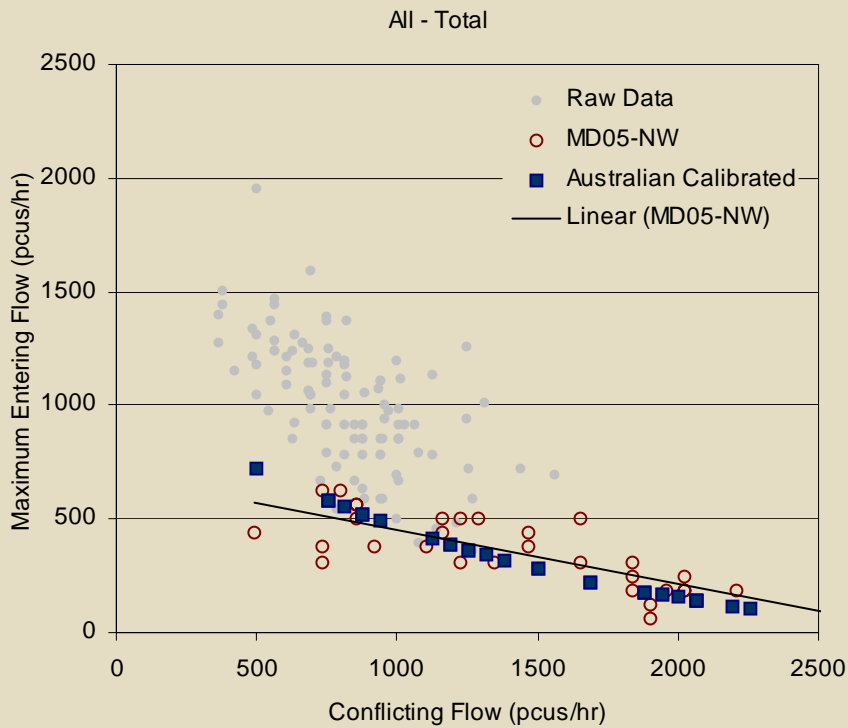
Multilane Calibration

- **British – All multilane approaches**
- **Total approach model**



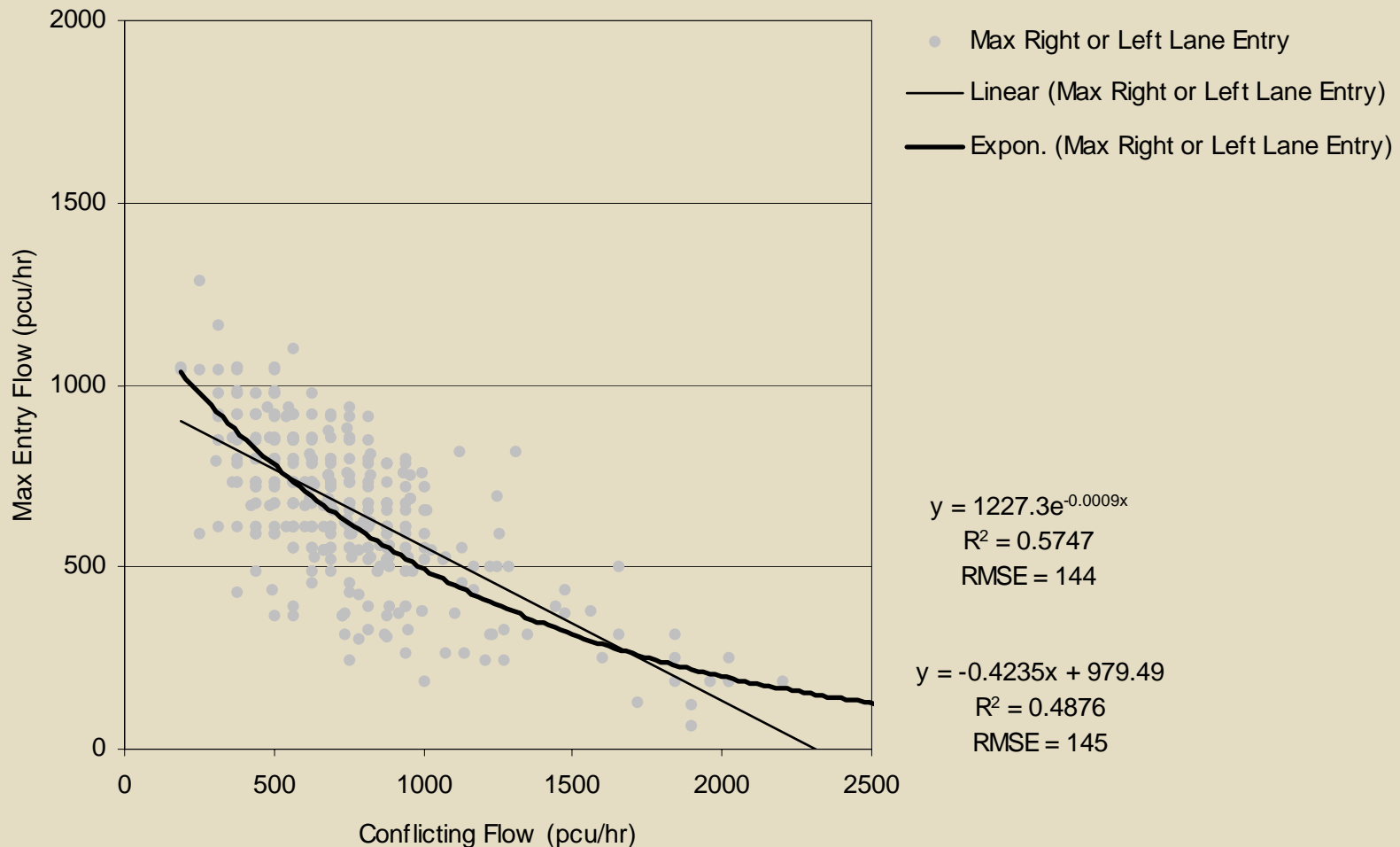
Multilane Calibration

■ Single lane entry – correlation to entry width



Multilane Calibration

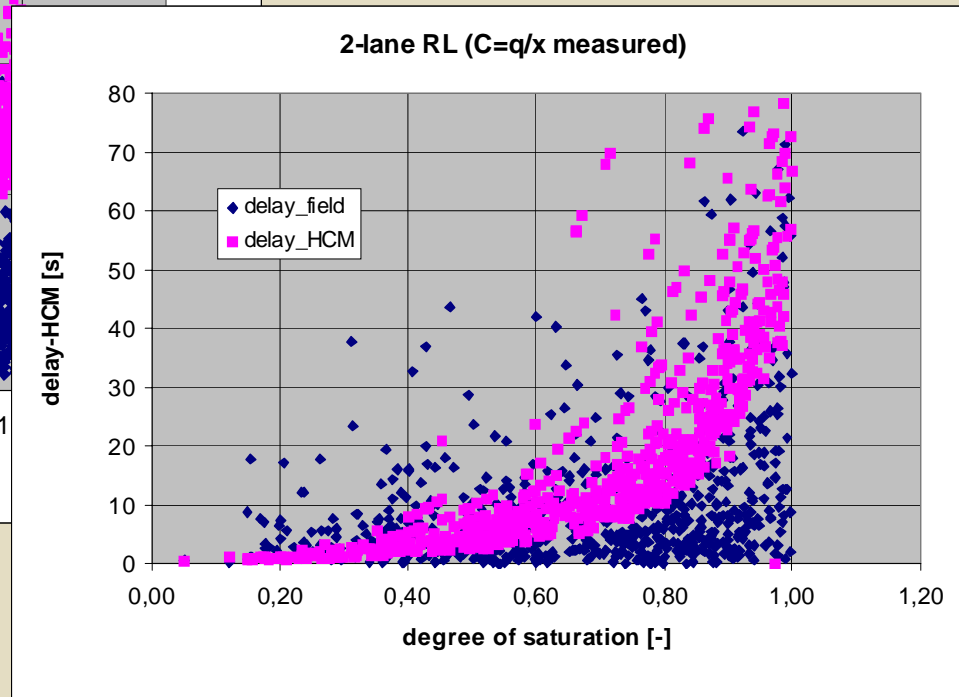
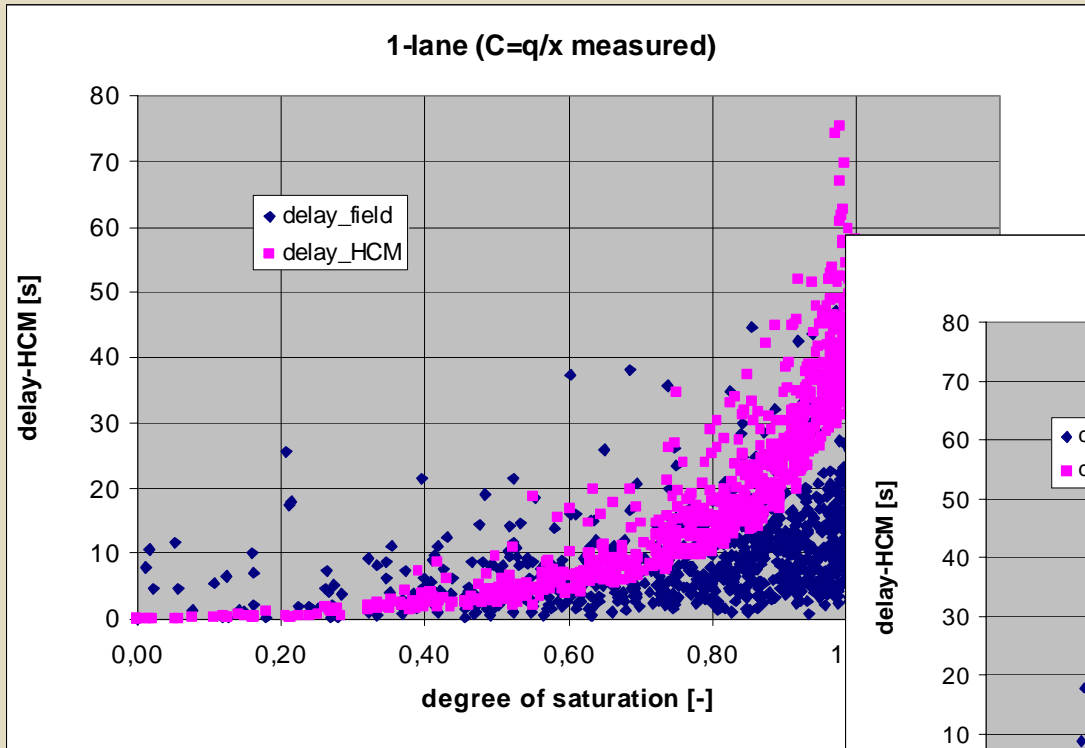
■ Critical lane model - Capacity of critical lane of two-lane approach



Delay

- **HCM delay tested against field data**
- **Data collection limits true understanding of delay for high v/c ;**
- **For $v/c > 0.9$; HCM difficult to estimate because initial queue is unknown**
- **Variation large; correlation factor = 0.44**
- **Recommendation: HCM delay equation appears to be reasonably valid**

Delay



HCM Draft Chapter Recommendations

- **1-Lane : HCM Model (revised parameters)**
- **Multi-Lane : Simple regression model for critical lane**
- **Delay : HCM Formulae**
- **Additional effort to explain findings in the HCM chapter:**
 - *Description of first order parameters*
 - *Description of the lack of correlation to geometry*